

Mechanics: Lagrangian Mechanics

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I. MOTION OF SYMMETRIC TOP WITH ONE POINT FIXED

$$T = \frac{1}{2} \sum_{i=1}^3 I_i \omega_i^2 = \frac{1}{2} I_1 (\omega_1^2 + \omega_2^2) + \frac{1}{2} I_3 \omega_3^2.$$

$$\omega_1^2 + \omega_2^2 = (\dot{\phi} \sin \theta \sin \psi + \dot{\theta} \cos \psi)^2 + (\dot{\phi} \sin \theta \cos \psi - \dot{\theta} \sin \psi)^2 = \dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2.$$

$$L = \frac{I_1}{2} (\dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2) + \frac{I_3}{2} (\dot{\phi} \cos \theta + \dot{\psi})^2 - Mgh \cos \theta.$$

$$p_\phi = \frac{\partial L}{\partial \dot{\phi}} = (I_1 \sin^2 \theta + I_3 \cos^2 \theta) \dot{\phi} + I_3 \dot{\psi} \cos \theta = \text{constant}.$$

$$p_\psi = \frac{\partial L}{\partial \dot{\psi}} = I_3 (\dot{\psi} + \dot{\phi} \cos \theta) = I_3 \omega_3 = \text{constant}.$$

$$E = \frac{I_1}{2} (\dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2) + \frac{I_3}{2} (\dot{\phi} \cos \theta + \dot{\psi})^2 + Mgh \cos \theta.$$

$$\dot{\psi} = \frac{p_\psi - I_3 \dot{\phi} \cos \theta}{I_3}.$$

$$\dot{\phi} = \frac{p_\phi - p_\psi \cos \theta}{I_1 \sin^2 \theta}.$$

$$\dot{\psi} = \frac{p_\psi}{I_3} - \frac{p_\phi - p_\psi \cos \theta}{I_1 \sin^2 \theta} \cos \theta.$$

$$\begin{aligned}
E &= \frac{I_1}{2}(\dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2) + \frac{I_3}{2}(\dot{\phi} \cos \theta + \dot{\psi})^2 + Mgh \cos \theta \\
&= \frac{I_1}{2}(\dot{\phi}^2 \sin^2 \theta + \dot{\theta}^2) + \frac{p_\psi^2}{I_3} + Mgh \cos \theta,
\end{aligned}$$

$$E' = E - \frac{p_\psi^2}{I_3} = \frac{I_1}{2}\dot{\theta}^2 + \frac{(p_\phi - p_\psi \cos \theta)^2}{2I_1 \sin^2 \theta} + Mgh \cos \theta.$$

$$V(\theta) = \frac{(p_\phi - p_\psi \cos \theta)^2}{2I_1 \sin^2 \theta} + Mgh \cos \theta.$$

$$x = \cos \theta.$$

$$V(x) = \frac{(p_\phi - p_\psi x)^2}{2I_1(1 - x^2)} + Mghx.$$

$$t(\theta) = \int \frac{d\theta}{\sqrt{\frac{2}{I_1} [E' - V(\theta)]}}.$$

$$\frac{dV}{d\theta} = \frac{-\cos \theta (p_\phi - p_\psi \cos \theta)^2 + p_\psi \sin^2 \theta (p_\phi - p_\psi \cos \theta)}{I_1 \sin^3 \theta} - Mgh \sin \theta.$$

$$\beta = p_\phi - p_\psi \cos \theta_0.$$

$$\cos \theta_0 \beta^2 - p_\psi \sin^2 \theta_0 \beta + Mgh I_1 \sin^4 \theta_0 = 0.$$

$$\beta = \frac{p_\psi \sin^2 \theta_0}{2 \cos \theta_0} \left(1 \pm \sqrt{\frac{4Mgh I_1 \cos \theta_0}{p_\psi^2}} \right).$$

$$1 \pm \sqrt{\frac{4Mgh I_1 \cos \theta_0}{p_\psi^2}} \geq 0. \implies p_\phi^2 \leq 4Mgh I_1 \cos \theta_0 \implies \omega_3 \geq \frac{2}{I_3} \sqrt{Mgh I_1 \cos \theta_0}.$$

$$\dot{\phi}_0 = \frac{\beta}{I_1 \sin^2 \theta_0}.$$

If $\frac{4Mgh I_1 \cos \theta_0}{p_\psi^2} \ll 1$ then

$$\begin{aligned}
\beta_+ &\sim \frac{p_\psi \sin^2 \theta_0}{\cos \theta_0} \longrightarrow \dot{\phi}_0^+ \sim \frac{I_3 \omega_3}{I_1 \cos \theta_0}, \\
\beta_- &\sim \frac{p_\psi \sin^2 \theta_0}{\cos \theta_0} \frac{2Mgh I_1 \cos \theta_0}{p_\psi^2} = \frac{Mgh I_1 \sin^2 \theta_0}{I_3 \omega_3} \longrightarrow \dot{\phi}_0^- \sim \frac{Mgh}{I_3 \omega_3}.
\end{aligned}$$